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# Machine Learning and the GR2M Model for Monthly Runoff Forecasting

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### Abstract

This article presents the results of an analysis of monthly rainfall into monthly runoff using Machine Learning algorithms, including Multiple Linear Regression, Multilayer Perceptron, and Support Vector Machine, which were compared with the GR2M hydrologic model to identify the most suitable approach for rainfall-runoff analysis in watersheds in the lower southern region of Thailand. This region is characterized by its unique geographic location at the border between Thailand and Malaysia. It faces challenges due to uncertainty in rainfall data, measured only on the Thai side, leading to a lack of corresponding data from Malaysia. The analysis found that the Machine Learning Support Vector Machine algorithm consistently provided the most accurate results across all sub-basins. Sub-basin TU02 achieved an MAE of 2.63 mm/month, while sub-basin X.119A had an MAE of 68.10 mm/month, sub-basin X.184 had an MAE of 145.05 mm/month, and sub-basin X.274 had an MAE of 66.08 mm/month. This research demonstrated the utility of advanced algorithms in rainfall-runoff analysis for areas with partial or incomplete data coverage. The findings confirm that the Machine Learning Support Vector Machine algorithm outperformed the Hydrologic Model (GR2M) in terms of accuracy and reliability. Therefore, this study concludes that applying the Machine Learning Support Vector Machine algorithm is an optimal approach for runoff prediction in the southern region of Thailand and provides a framework for potential applications in other areas with similar data and geographic challenges.

Keywords: Hydrologic Model; Runoff Forecasting; Machine Learning; GR2M; Thailand.

## 1. Introduction

The hydrologic assessment of rainfall-runoff is a complex process, especially in watersheds with national boundaries, where the constraints of rainfall measurements due to such boundaries can affect the accuracy of runoff estimates. Key factors contributing to errors include the lack of comprehensive temporal data for model calibration [1, 2] and the incompleteness of constants used in analytical processes [3, 4]. Furthermore, variability in inconsistent rainfall data increases the risk of errors, especially in regions with diverse geographical features, such as surface runoff loss and streamflow changes due to land-use modifications [5], soil permeability variations [6, 7], and evapotranspiration [8, 9]. Another issue to consider is climate and land use changes, which affect the water balance in river basins, locally and globally. Such changes are likely to increase the intensity of heavy rainfall and the frequency of flood events. For

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example, studies in the Yellow River basin [10], Kunhar [11], and Fujiang [12] found that changes in rainfall and land use affected water flow in the basin [13]. Moreover, changes in water resource management patterns also play an important role in mitigating the impacts of this variability, especially in vulnerable areas [10, 12].

In terms of model evaluation, various models such as HEC-HMS [14, 15], SWAT [16, 17], NAM [18, 19], and GR2M [20-22] are currently being used to estimate rainfall and runoff. Model performance comparisons, such as HEC-HMS with SWAT [23, 24] and GR2M [25], demonstrate the need to select an appropriate model to increase accuracy [26]. Meanwhile, the application of Machine Learning (ML), such as MLR, MLP, and SVM, in runoff forecasting has become increasingly popular due to its ability to handle more data than traditional hydrologic models [27, 28].

For Thailand, GR2M and ML have been applied to forecast runoff in the upper southern region [29-31]. However, the border area between Thailand and Malaysia, the Lower Part of the Peninsula – East Coast River basin of Thailand, is still an area of geographic complexity and limited rainfall data from Malaysia, resulting in high error rates for runoff analysis accuracy. Therefore, using ML algorithms is an important alternative because several studies confirm that ML can improve accuracy better than the GR2M model in certain cases [29, 32]. This study aims to explore the efficiency of GR2M and ML in forecasting runoff in the border basin between Thailand and Malaysia, which has never been analyzed before. The focus is on selecting the most appropriate model for warning flood risk areas and supporting water resource management during flash floods or droughts. In the future, rainfall forecasts provided by the Thai Meteorological Department and the Hydro-Informatics Institute (Public Organization) could be incorporated into the system to predict runoff in advance if the model achieves high accuracy. This integration would enhance the disaster warning system, enabling timely and accurate alerts for flood-prone areas. The expected results are models that improve runoff forecasting, support long-term water management, promptly warn of disasters, and reduce the impact on life, property, and ecosystems in risk areas, with the potential to be applied in other regions with similar topography and data limitations.

## 2. Study Area and Data Set

This study focuses on the lower eastern coast of Thailand, which forms a transboundary basin between Thailand and Malaysia. It is located in the southernmost part of Thailand, consisting of Pattani, Yala, Narathiwat, and parts of Songkhla provinces [33, 34]. The western and southern parts of the basin are adjacent to the Sankalakhiri mountain range, the border between Thailand and Malaysia. The direction of the river flow is from the south to the north and flows into the Gulf of Thailand. Most of the area is forested and mountainous, while the lower part of the basin is flat. The average elevation of the basin is between 0 and 1,535 MSL. The basin area measures 10,605 square kilometers, with the north and east bordering the Gulf of Thailand, the west bordering the Songkhla Lake Basin, and the south bordering Malaysia [35]. The southwest monsoon and northeast monsoon influence the area. In addition, occasional tropical depressions and typhoons come from the South China Sea, resulting in different seasons: the rainy season occurs from May to January, and the hot season occurs from February to April.

Monthly meteorological and hydrological data were collected from various central agencies, such as climate data and evaporation data from the Meteorological Department(TMD) and Hydro-Informatics Institute (Public Organization: HII), with monthly rainfall at 8 stations: BTGH(2017-2023), TU02(2017-2023), VLGE35(2017-2023), STH019(2017-2023), STH013(2017-2023), STH014(2017-2023), BUKT(2018-2023), STH021(2018-2023), and runoff data from 2 agencies, the Royal Irrigation Department(RID) and the Electricity Generating Authority of Thailand(EGAT), consisting of 4 stations: X.184, X.119A, X.274, TU02. Runoff data also came from the Royal Irrigation Department at 3 stations: X. 184 Saiburi River (SBR), X.119A Golok River (KLR-1), and X.274 Golok River (KLR-2). From the Electricity Generating Authority of Thailand, data came from 1 station at TU02 Pattani River (Pattani River: PTR), as shown in Figure 1.

In summary, the physical geographical characteristics of the studied river basin are as follows. The river basin area (A) had values of 225.49-1260.04 square kilometers. The main river (L) length ranged from 23.58 to 69.52 kilometers (Table 1). The length of the main river to the center of gravity of the basin (Lc) was 5.52 - 31.52 kilometers. The slope of the basin (S) was 0.00108-0.02649. The From Factor (FF) was 0.2320 - 0.4055, and the Elongation ratio (ER) was between 0.5434 - 0.7183. The From Factor (FF) is the ratio of watershed area to the square of the watershed length. The elongation ratio is the ratio of the diameter of a circle in the same area as the basin to the maximum basin length (1.128A0.5/L), as shown in Table 2.

No.	<b>Runoff Station</b>	Period	Sub-Basin	A (km²)	L (km)	Lc (km)	S	FF	ER
1	X.184	2017-2023	SBR	1260.04	69.52	21.67	0.00108	0.2607	0.5760
2	X.119A	2018-2023	KLR-1	913.39	62.74	31.52	0.02649	0.2320	0.5434
3	X.274	2017-2023	KLR-2	225.49	23.58	5.52	0.00993	0.4055	0.7183
4	TU02	2017-2023	PTR	729.17	43.56	21.16	0.00367	0.3844	0.6993

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Figure 1. Location of rainfall and runoff stations in the study area

<b>Runoff Station</b>	Sub-basin	Rain Gauge Stations	Area (sq. km)	Weightage factor: wf	
	KLR-1	BUKT	525.94	0.576	
X.119A		STH021	322.35	0.353	
		STH014	65.10	0.071	
	PTR	BTGH	460.44	0.632	
TU02		TU02	145.81	0.200	
		VLGE35	122.92	0.169	
	SBR	STH013	528.87	0.420	
V 194		STH014	442.79	0.351	
A.104		STH019	266.14	0.211	
		BUKT	22.24	0.018	
X.274	KLR-2	BUKT	225.49	1.000	

Table 2. Proportion of rain gauge stations affecting sub-basins

# 3. Methodology and Prediction Model

## 3.1. Methodology

This article studies the prediction of monthly runoff using three data variables: monthly rainfall, monthly evaporation, and monthly runoff. It is the foremost information for predicting monthly runoff. It starts by determining the proportion of influence of rain stations using the Thiessen polygon method. This study used 8 rain stations: BUKT, STH021, STH014, BTGH, TU02, VLGE35, STH013, and STH019. Then, all data are normalized so that the value of each variable is between 0 and 1. Then, that data will be entered into the model to create a runoff prediction model. In this study, 4 models were chosen for comparison of performance: multiple linear regression, multilayer perceptron, support vector machine, and GR2M. When the model construction was completed, the results were compared to the performance of the models by using the correlation coefficient and mean absolute error, as shown in Figure 2.



Figure 2. Block diagram of the modeling processes

#### 3.2. Multiple Linear Regression

Multiple linear regression is a data analysis tool used to identify the relationship between a dependent variable and multiple independent variables. It takes advantage of the linear nature of these relationships to make predictions. A multiple linear regression equation represents the quantitative relationship between variables and can be presented as an equation, such as Equation 1 below.

$$y_i = \beta_0 = \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \dots + \beta_n x_n + \epsilon \tag{1}$$

where  $y_i$  is the dependent variable,  $\beta_0$  and  $\beta_i$  are the intercept and coefficient of regression, respectively,  $x_i$  represents an independent variable, and  $\epsilon$  is the error term [36].

## 3.3. Multilayer Perceptron

There are many types of artificial neural networks (ANN), including the multi-layer perceptron (MLP) [37], which comprises multiple layers of fully connected nodes. An MLP is composed of an input layer, one or more hidden layers, and an output layer, as illustrated in Figure 3. Activation functions play a crucial role by introducing non-linearity to the model and are applied to the nodes of the hidden and output layers [38-40]



Figure 3. Multilayer perceptron

## 3.4. Support vector machine

The Support Vector Machine (SVM) is a widely prevalent supervised learning algorithm for regression and classification analysis. One of the key features of SVM is its ability to apply kernel functions to handle data that are linearly indivisible in the original dimensions. Commonly used kernel functions include linear, polynomial, and radial basis functions (RBF). The main goal of SVM is to find the most suitable hyperplane to separate the data into distinct clusters by optimizing the distance between the hyperplane and the nearest data point from each cluster. This distance is called the "margin," and the data points are called the "support vectors," as shown in Figure 4 [41].



Figure 4. Support Vector Machine

## 3.5. GR2M

The GR2M model is a simple-to-use monthly rainfall and runoff model developed in the late 1980s with only two parameters: the ability to keep moisture in the soil  $(X_1)$  and the water exchange coefficient  $(X_2)$ . The model requires three observed meteorological and hydrological inputs, including monthly rainfall, evapotranspiration, and runoff. Figure 5 shows the structure of the GR2M model, and the calculations for monthly rainfall and runoff are given in Equations 2 to 9 [42-44].



Figure 5. Structure of the GR2M model [31]

$$S_1 = \frac{S + X_1 \varphi}{1 + \varphi \frac{S}{X_1}} \text{ with } \varphi = \tanh(\frac{P}{X_1})$$
(2)

$$P_1 = P + S + S_1 \tag{3}$$

$$S_{2} = \frac{S_{1}(1-\psi)}{1+\psi(1+\frac{S_{1}}{X_{1}})} \text{ with } \psi = \tanh(\frac{E}{X_{1}})$$
(4)

$$S = \frac{S_2}{(1 + (\frac{S_2}{X_1})^3)}$$
(5)

$$P_3 = P_1 + P_2 \tag{6}$$

$$R_1 = R + P_3 \tag{7}$$

$$R_2 = X_2 \times R_1 \tag{8}$$

$$Q = \frac{R_2^2}{R_2 + 60}$$
(9)

where  $S_1$  is the storage component, P is precipitation, E is evaporation, S is accumulated storage,  $S_1$  is the primary storage component (Production store),  $S_2$  is a secondary storage component (Routing store),  $P_1$  is net precipitation in the first step,  $P_2$  is net precipitation passing through  $S_2$ ,  $P_3$  is additional precipitation-related flow contributing to runoff,  $R_1$  is total runoff in the first step,  $R_2$  is total runoff in the final step, Q is the discharge rate,  $X_1$  is a system capacity parameter for storage and non-linear relationships, and  $X_2$  is the coefficient related to the transformation from  $R_1$  to  $R_2$ .

## 3.6. Model Evaluation

In this research, statistical indicators were used to evaluate the performance of each model using two methods comprising mean absolute error (MAE), which considers the average absolute error between the observed and simulated values, and correlation coefficient (r), which is the linear relationship between two variables.

$$MAE = \frac{\sum_{i=1}^{n} |R_{obs} - R_{Pred}|}{n} \tag{10}$$

$$r = \frac{\sum_{l=1}^{n} (R_{Obs} - \bar{R}_{Obs})(R_{Pred} - \bar{R}_{Pred})}{\sqrt{\sum_{l=1}^{n} (R_{Obs} - \bar{R}_{Obs})^2} \sqrt{\sum_{l=1}^{n} (R_{Pred} - \bar{R}_{Pred})^2}}$$
(11)

where  $R_{obs}$  is observed runoff,  $R_{pred}$  is predicted runoff, n is the amount of data or number of time periods,  $\overline{R}_{obs}$  is average actual runoff,  $\overline{R}_{pred}$  is average predicted runoff.

## 4. Results and Discussion

## 4.1. Thiessen Polygon

In Figure 6, the weighting factor (wf) of the rain gauge stations in the area is analyzed using the Thiessen Polygon method to estimate the average rainfall in each sub-basin using data from 8 rain gauge stations: BUKT, STH021, STH014, BTGH, TU02, VLGE35, STH013, and STH019.



Figure 6. Thiessen polygon

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Table 2 shows the details of the weighting factor (wf), which can be used to calculate the average rainfall in each sub-basin. It was found that each sub-basin had a different share of rain gauge stations, resulting in different weighting factor (wf) values for rainfall monitoring stations. For example, the KLR-1 sub-basin has three rainfall monitoring stations: BUKT, STH021, and STH014. It was found that BUKT has the highest weighting factor (wf) value of 0.576, followed by STH021 with a wf value of 0.353 and STH014 with a wf value of 0.071.

### 4.2. Compression Prediction Runoff Model

This research developed a model for forecasting monthly runoff volume from 8 rain gauge stations and evaporation data in 4 sub-basins, namely PTR, KLR-1, SBR, and KLR-2. The study compared the results of 4 models, consisting of Multiple Linear Regression (MLR), Multilayer Perceptron (MLP), Support Vector Machine (SVM) with Kernel Functions of Linear, Polynomial, and Radial Basis Function (RBF), and the GR2M model. The results can be considered for each sub-basin as follows:

The monthly runoff forecast results in the Pattani River Sub-basin (PTR) found that training the model using the support vector machine with a Radial Basis Function kernel: SVM(rbf) kernel had the best prediction performance with an MAE value of 2.47 mm/month, and the model testing using multi-layer perceptron: MLP and support vector machine with the linear kernel: SVM(linear) had the best prediction performance with MAE value of 2.61 and 2.63 mm/month, respectively, which provides higher accuracy than the GR2M method with an MAE value of 7.33. The details are shown in Figures 7 to 11, and Table 3.



Figure 7. Pattani River Sub-basin (PTR)



Figure 8. Golok River Sub-basin, Central Part (KLR-1)



Figure 9. Saiburi River Sub-basin (SBR)



Figure 10. Golok River Sub-basin, Upper Part (KLR-2)



A. Train

B. Test

Figure 11. Pattani River Sub-basin (PTR)

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The monthly runoff forecast results in the Golok River Sub-basin, Central Part (KLR-1) found that training the model using the support vector machine with a polynomial kernel: SVM(poly) offered the best prediction performance, with an MAE value of 45.04 mm/month. Testing the model using the support vector machine with a linear kernel: SVM(linear) will have the best prediction performance, with an MAE value of 68.10 mm/month which gives higher accuracy than the GR2M method with an MAE value of 116.45. The details are shown in Figures 8 and 12, and Table 3.





The monthly runoff forecast results in the Saiburi River Sub-basin (SBR) found that training the model using the support vector machine with a linear kernel: SVM(linear) had the best prediction performance, with an MAE value of 91.85 mm/month. Testing the model using the support vector machine with a polynomial kernel: SVM(poly) will have the best prediction performance, with an MAE value of 145.05 mm/month which gives higher accuracy than the GR2M method with an MAE value of 736.80. The details are shown in Figures 9 and 13, and Table 3.



Figure 13. Saiburi River Sub-basin (SBR)

The monthly runoff forecasting results in the Golok River Sub-basin, Upper Part (KLR-2) found that training the model and testing the model using a support vector machine with linear kernel: SVM (linear) will have the best prediction performance, with MAE values of 59.35 and 66.08 mm/month, respectively, which gives higher accuracy than the GR2M method, which has an MAE value of 175.95. The details are shown in Figures 10 and 14, and Table 3.



### Figure 14. Golok River Sub-basin, Upper Part (KLR-2)

			MLP	MLR	SVM (linear)	SVM (rbf)	SVM (poly)	GR2M
PTR	Train	R	0.84	0.82	0.82	0.93	0.88	0.83
		MAE	3.13	3.21	3.25	2.47	2.65	3.96
	Test	R	0.79	0.76	0.75	0.77	0.54	0.91
		MAE	2.61	3.33	2.63	3.32	4.09	7.33
KLR-1	Train	R	0.89	0.89	0.88	0.91	0.90	0.89
		MAE	45.45	46.74	48.21	46.70	45.04	45.76
	Test	R	0.77	0.79	0.76	0.75	0.78	0.85
		MAE	73.11	82.97	68.10	77.65	172.67	116.45
SBR	Train	R	0.41	0.70	0.70	0.74	0.69	0.67
		MAE	144.48	92.77	91.85	91.99	96.48	305.58
	Test	R	0.64	0.84	0.84	0.57	0.79	0.93
		MAE	231.93	166.86	159.19	157.77	145.05	736.80
KLR-2	т :	R	0.77	0.79	0.79	0.85	0.77	0.82
	Train	MAE	65.76	61.52	59.35	60.05	67.75	75.48
	Test	R	0.76	0.85	0.83	0.74	0.93	0.95
		MAE	72.61	77.55	66.08	70.96	77.19	175.95

Table 3	3.	Perf	formance	comparison
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As a comparison, it was found that both studies support that SVM(rbf) had the highest efficiency in forecasting monthly runoff when the results were compared with the research [31], especially in areas with complex or low-quality data such as the PTR and KLR-1 river basins. In this research, SVM(rbf) had the lowest MAE (2.47 mm/month and 45.04 mm/month), and the research [28] gave an average NSE of 0.595 and average r of 0.805, which were the best in the validation step. Both studies also showed that Kernel Functions significantly affected the accuracy of SVM, with SVM(rbf) being suitable for non-linear data. At the same time, GR2M, despite being easy to use, gave significantly lower results than other MLS (average NSE of 0.566 and average r of 0.760), especially in cases where the data had low correlation between variables.

## 5. Conclusion

This article studies the development of models to predict runoff in the lower eastern region of southern Thailand, which consists of 4 sub-basins comprising the PTR sub-basin, KLR-1 sub-basin, SBR sub-basin, and KLR-2 sub-basin. In this paper, 4 models are used to predict monthly runoff: multivariate linear regression, multi-class perceptron, support vector machine, and GR2M. In the PTR sub-basin, SVM(rbf) gives the lowest MAE (2.47 mm/month) and the highest r (0.93), which means the best forecasting performance in the Training Phase. MLP and SVM(linear) have the lowest MAE (2.61 mm/month), but SVM(rbf) has a higher r-value of 0.77, indicating a more accurate prediction in terms of a linear relationship. GR2M has the lowest MAE and r, indicating that its performance is unsuitable in this basin for the Testing Phase. Therefore, the model SVM(rbf) is the most suitable for training, and MLP/SVM(linear) has equivalent

predictive ability in testing. In the KLR-1 sub-basin, SVM(poly) gave the lowest MAE (45.04 mm/month) and the highest r value (0.91) for the Training Phase. In the Testing Phase, SVM(linear) had the lowest MAE (68.10 mm/month), but SVM(rbf) had a higher r-value (0.77), and GR2M had the highest MAE (116.45 mm/month), indicating the lowest performance. Therefore, SVM(poly) is the most suitable for training, but SVM(linear) performs best in the Testing Phase. In the SBR sub-basin, SVM(linear) gave the lowest MAE (91.85 mm/month) and the highest r value (0.84) for the Training Phase. For the Testing Phase, SVM(poly) gave the lowest MAE (145.05 mm/month), with GR2M having the highest MAE (736.80 mm/month), indicating the lowest performance. Although SVM(linear) performed best in the training phase, SVM(poly) provided more accurate predictions in the testing phase. In the KLR-2 sub-basin, SVM(linear) gave the lowest MAE (66.08 mm/month) and the highest r value (0.83), while GR2M had the highest MAE (175.95 mm/month), indicating the lowest performance. From the results in this sub-basin, SVM(linear) gave the lowest MAE (66.08 mm/month) and the highest r value (0.83), while GR2M had the highest MAE (175.95 mm/month), indicating the lowest performance. From the results in this sub-basin, SVM(linear) was found to be the most suitable model in both the training and testing phases.

Simpler watersheds like PTR and KLR-2 benefited from kernels such as RBF and Linear due to their ability to efficiently model uniform hydrological patterns. In contrast, more diverse and complex watersheds, such as KLR-1 and SBR, required the flexibility of Polynomial Kernel to account for their variability and structured non-linear dynamics. These results emphasize the necessity of choosing a kernel that aligns with the distinct hydrological features of each watershed to maximize predictive accuracy.

The results of the accuracy analysis for each model in this research can be used with the 3-day rainfall forecast data prepared by the Thai Meteorological Department and the Hydro-Informatics Institute (Public Organization) of Thailand to use with this model to forecast water volume in the future, which will help increase the efficiency of disaster warning systems in both Thailand and Malaysia. In addition, such integration may help develop a natural disaster monitoring system in flood-prone border areas of ASEAN member countries, enabling timely and accurate warning of flood-prone areas to reduce potential damage in ASEAN member countries.

## 6. Declarations

## 6.1. Author Contributions

Conceptualization, B.C. and K.A.N.; methodology, KW.N., S.K., and K.A.N.; software, K.W.N. and S.K.; validation, B.C., K.A.N., and S.K.; formal analysis, B.C. and K.A.N.; investigation, B.C. and K.A.N.; resources, B.C. and K.A.N.; data curation, B.C., K.T., and S.K.; writing—original draft preparation, K.A.N. and B.C.; writing—review and editing, K.A.N. and B.C.; visualization, K.T. and S.K.; supervision, B.C. and K.A.N.; project administration, K.A.N.; funding acquisition, K.A.N. All authors have read and agreed to the published version of the manuscript.

## 6.2. Data Availability Statement

The data presented in this study are available in the article.

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#### 6.5. Conflicts of Interest

The authors declare no conflict of interest.

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